



Concepts of Programming Language Design

Abstract Machines

Gabriele Keller
Tom Smeding

Abstract Machines

- What is an abstract machine?
 - a set of legal **states**
 - ▶ **final** and **initial** states as subset
 - A set of **instructions** altering the state of the machine
 - ▶ it should be possible to implement the operations on a real machine in a finite (preferably constant) number of steps
- Why use abstract machines at all?
 - specifies the semantics of a programming languages
 - can specify architecture independent implementation
- We have seen this before
 - similar to SOS, but with abstract machines, we care about performance

Control Flow

- Base line: the M-machine
 - small step semantics for MinHs
 - transition system embodies essentially a very high-level (= concise, but inefficient) abstract machine
 - we'll call it the **M-machine** from now on, to distinguish it from other abstract machines for MinHs
- Characteristics of the M-machine
 - substitution as “machine operation”
 - ▶ why is that not inefficient?
 - ▶ can be avoided by using an environment
 - control-flow is not explicit
 - ▶ the search rules determine next subexpression to be evaluated
 - ▶ why is that inefficient?

Control Flow

- Example:

$$\frac{}{(\text{Plus } (\text{Num } n) (\text{Num } m)) \mapsto (\text{Num } (n + m))}$$

$$e_2 \mapsto e_2'$$

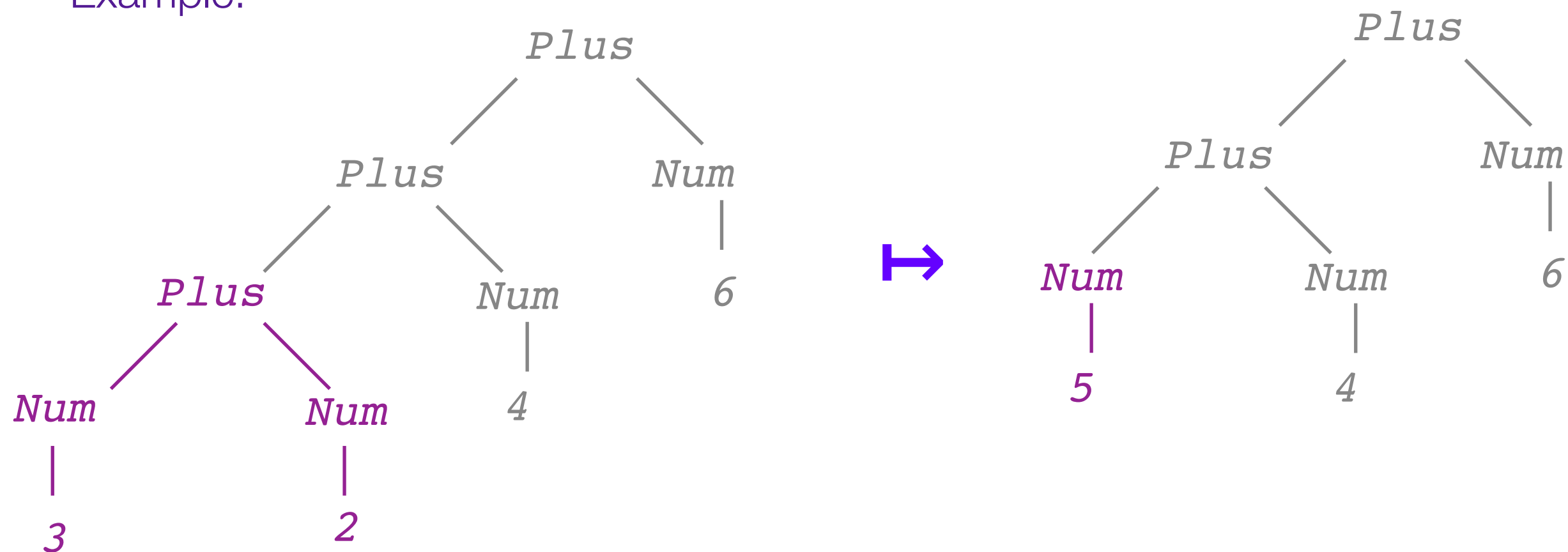
$$\frac{}{(\text{Plus } (\text{Num } n) e_2) \mapsto (\text{Plus } (\text{Num } n) e_2')}$$

$$e_1 \mapsto e_1'$$

$$\frac{}{(\text{Plus } e_1 e_2) \mapsto (\text{Plus } e_1' e_2')}$$

Control Flow

- Example:



$Plus(Num\ 3)(Num\ 2) \mapsto Num\ 5$

$Plus(Plus(Num\ 3)(Num\ 2))(Num\ 4) \mapsto Plus(Num\ 5)(Num\ 4)$

$Plus(Plus(Plus(Num\ 3)(Num\ 2))(Num\ 4))(Num\ 6) \mapsto Plus(Plus(Num\ 5)(Num\ 4))(Num\ 6)$

depending on the size & nesting depth of the expression,
searching for the next reducible subexpression can be very
expensive!!!



Control Flow

- Single-step evaluation in Haskell:

```
data Expr
  = Num    Int
  | Plus   Expr Expr
  | Times  Expr Expr
```

```
single (Plus (Num n1) (Num n2)) =
  Num (n1 + n2)
single (Plus (Num n1) e) =
  Plus (Num n1) (single e)
single (Plus e1 e2) =
  Plus (single e1) e2
```

```
bigStep :: Expr -> Int
bigStep (Num n)
  = n
bigStep (Plus e1 e2)
  = (bigStep e1) + (bigStep e2)
```

```
n
(single e)
```

- ▶ for each step, the expression has to be traversed to find the next subexpression that has to be evaluated
- ▶ makes heavy use of Haskell's runtime stack



The C-machine

- Explicit control flow: C-machine
 - explicit **stack**
 - explicit **handling of control flow**
 - variable binding still handled by substitution
 - we call this machine the **C-machine**
- Machine state
 - the current expression (as before)
 - **a control stack of subcomputations** (frames) which have to be performed before the machine terminates
- Initial and final states
 - **initial states**: closed expression and **an empty stack**
 - **final states**: expression is a value and **the stack is empty**

The C-machine

- Example: addition in three stages

1. Evaluate first argument

- ▶ first argument becomes current expression
- ▶ remember to continue with computation, result as first argument

2. Evaluate second argument

- ▶ second argument becomes current expression
- ▶ remember to continue with computation, result as second argument

3. Perform addition

The C-machine

- How can we denote a stack frame as a term?
- We use terms with holes; e.g.,

$(\text{Plus } \square \ e_2)$

- ▶ suspended computation of addition
- ▶ waits for the value of its first argument

- Inductive definition of frames:

$$\frac{e \text{ expr}}{(\text{Plus } \square \ e) \text{ frame}}$$
$$\frac{v \text{ value}}{(\text{Plus } v \ \square) \text{ frame}}$$

$(\text{Plus } e_1 \ \square)$ not a frame,
because first argument is
evaluated first!

The C-machine

- Alternatively, we could have different operators for the three different variants of plus frames:

$$\frac{e \text{ expr}}{\text{(Plus } \square \text{ } e) \text{ frame}}$$
$$\frac{v \text{ value}}{\text{(Plus } v \text{ } \square) \text{ frame}}$$

$$\frac{e \text{ expr}}{\text{(Plus1 } e) \text{ frame}}$$
$$\frac{v \text{ value}}{\text{(Plus2 } v) \text{ frame}}$$

- The first representation makes it easier to see what is missing, but the two representations are equivalent



Inductive Definition of Frames

- Addition

$$\frac{e \text{ expr}}{(\text{Plus } \square \ e) \text{ frame}}$$

$$\frac{v \text{ value}}{(\text{Plus } v \ \square) \text{ frame}}$$

- If-expressions

$$\frac{e_1 \text{ expr} \quad e_2 \text{ expr}}{(\text{If } \square \ e_1 \ e_2) \text{ frame}}$$

- Application (same as addition, just replace operator)
- No frames for `Recfun` (they are expressions/values)



Example of frames

(Plus □ (Num 3))

(Plus □ (Plus (Num 2) (Num 3)))

(Plus □ (If (Const False) (Num 2) (Num 3)))

(Plus (Num 2) □)

~~*(Plus (Plus (Num 4) (Num 2)) □)*~~

(If □ (Num 2) (Num 3))

(Apply (Recfun Int Int (x. Plus x x)) □)

(Apply □ (Plus (Num 3) (Num 4)))

Stack and Machine Modes

- Stacks: $f_1 \triangleright f_2 \triangleright \circ$
 - f_1 is the top-most frame
 - f_2 is the second frame
 - $\circ$ is the empty stack
- Inductive definition:

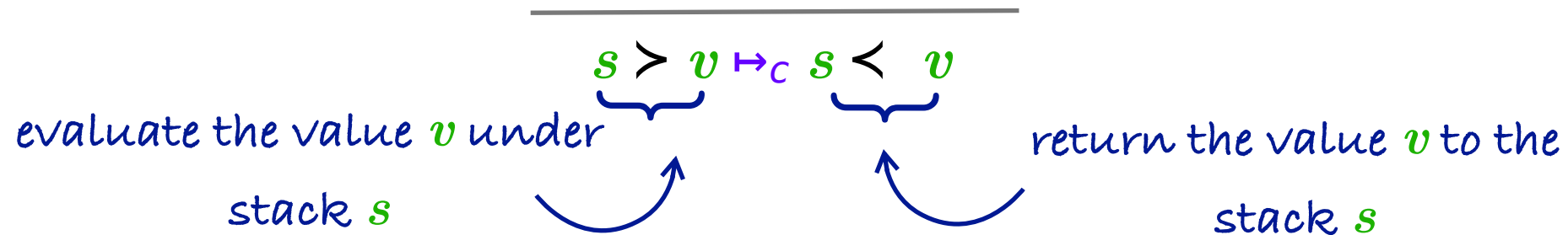
$$\frac{}{\circ \text{ stack}}$$
$$\frac{f \text{ frame} \quad s \text{ stack}}{f \triangleright s \text{ stack}}$$

- Machine modes: the C-machine operates in two modes:
 - ▶ $s > e$: **evaluate** expression e under stack s
 - ▶ $s < v$: **return** value v to stack s



Transition Rules for MinHs

- Values (integers, booleans, functions)



- Addition

$$\frac{}{s \triangleright (\text{Plus } e_1 e_2) \mapsto_c (\text{Plus } \square e_2) \triangleright s \triangleright e_1}$$

$$\frac{}{(\text{Plus } \square e_2) \triangleright s \triangleleft v \mapsto_c (\text{Plus } v \square) \triangleright s \triangleright e_2}$$

$$\frac{}{(\text{Plus } (\text{Num } n_1) \square) \triangleright s \triangleleft (\text{Num } n_2) \mapsto_c s \triangleleft (\text{Num } (n_1 + n_2))}$$



Transition Rules for MinHs

- if-expressions

$$\frac{}{s \triangleright (\text{If } e_1 \ e_2 \ e_3) \mapsto_c (\text{If } \square \ e_2 \ e_3) \triangleright s \triangleright e_1}$$

$$\frac{(\text{If } \square \ e_2 \ e_3) \triangleright s < \text{True}}{\mapsto_c} s \triangleright e_2$$

$$\frac{(\text{If } \square \ e_2 \ e_3) \triangleright s < \text{False}}{\mapsto_c} s \triangleright e_3$$



Transition Rules for MinHs

- Function application

$$s \triangleright (\text{Apply } e_1 \ e_2) \mapsto_c (\text{Apply } \square \ e_2) \triangleright s \triangleright e_1$$

$$(\text{Apply } \square \ e_2) \triangleright s < v \mapsto_c (\text{Apply } v \ \square) \triangleright s \triangleright e_2$$

$$(\text{Apply } \langle f.x.e \rangle \ \square) \triangleright s < v \mapsto_c s \triangleright e \ [f := \langle f.x.e \rangle, x := v]$$

from now on to save some space, we use a more compact notation for functions and drop the type arguments:

$\langle f.x.e \rangle$ instead of $(\text{Recfun } \tau_1 \ \tau_2 \ (f.x.e))$

- Observations;

- ▶ all the inference rules are **axioms**!
- ▶ the definition of single-step evaluation in the C-machine is **not recursive**
- ▶ the full evaluator is **tail recursive** (can be implemented using a while-loop)



Environments

- Now, let's get rid of substitution!
- Let's first look at a big step environment semantics

$$\frac{e_1 \Downarrow \langle f.x.e \rangle \quad e_2 \Downarrow v \quad e[f := \langle f.x.e \rangle, x := v] \Downarrow v'}{(\text{Apply } e_1 \ e_2) \Downarrow v'}$$

- Without substitution, we need an environment η for the evaluation
 - An environment η as is an ordered (possibly empty) sequence of bindings
 - Lookup (retrieves left-most entry): $\eta(x) = v$

$$\frac{}{\bullet \ env} \quad \frac{\eta \ env}{x = v, \eta \ env}$$

- Evaluation of expression e under environment η :

$$\eta \mid e \Downarrow v$$



Environments

- Big-step environment rule for application:

$$\frac{\eta(x) = v}{\eta \mid x \Downarrow v}$$

$$\frac{}{\eta \mid f.x.e \Downarrow \langle f.x.e \rangle}$$

$$\frac{\eta \mid e_1 \Downarrow \langle f.x.e \rangle \quad \eta \mid e_2 \Downarrow v \quad f = \langle f.x.e \rangle, x = v, \eta \mid e \Downarrow v'}{\eta \mid (\text{Apply } e_1 e_2) \Downarrow v'}$$



Environments

- Does this work?

```
(recfun addOne :: x = x + 1)) 15
```

```
(recfun add :: x =  
  recfun add' :: y = x + y)) 15 5
```



Environments

- Problem:
 - functions as return values may contain free variables, which escape their scopes
 - when the body is finally evaluated, the information what the free variables were bound to is not available anymore



Dealing with partial application

- Solution:

- we need to **bundle** returned functions **with current environment**
- we call this **a closure**
- requires a new form of return values:

environment which
was current when function
value was created

$\langle\langle \eta, f.x.e \rangle\rangle$



- Closures only appear as values during execution - there is no source form



Environments

- Big-step semantics rules for function values and application:

$$\frac{}{\eta \mid \langle f.x.e \rangle \Downarrow \langle\langle f.x.e, \eta \rangle\rangle}$$

$$\frac{\eta \mid e_1 \Downarrow \langle\langle f.x.e, \eta' \rangle\rangle \quad \eta \mid e_2 \Downarrow v \quad f = \langle\langle f.x.e, \eta' \rangle\rangle, x = v, \eta' \mid e \Downarrow v'}{\eta \mid (\text{Apply } e_1 \ e_2) \Downarrow v'}$$

Environments

- Closures are necessary whenever we have functions as return values, which contain variables bound outside that function
- Example: JavaScript

```
function createCounter() {  
    let count = 1; // This is the variable that will be remembered by the closure.  
  
    return function() { // This returned function forms a closure.  
        count++; // It accesses the `count` variable from its lexical scope.  
        return count;  
    };  
}
```

```
const counter1 = createCounter(); // Create a counter instance  
console.log(counter1());  
console.log(counter1());  
console.log(counter1());
```

```
const counter2 = createCounter();  
console.log(counter2());  
console.log(counter2());  
console.log(counter1());
```



Environments

- Let's get back to our C-machine and add environments:

$$(\text{Apply } \langle f.x.e \rangle \square) \triangleright s < v \quad \mapsto_c \quad s > e [f := \langle f.x.e \rangle, x := v]$$

- We also need an environment η as part of the state

$$s \mid \eta > e$$

$$s \mid \eta < v$$



Environments

- Just like in the big step semantics, we need to have a special rule for returning function values:

$$\begin{array}{ll} s \mid \eta \triangleright (\text{Num } n) & \mapsto_E s \mid \eta \triangleleft (\text{Num } n) \\ s \mid \eta \triangleright \langle f.x.e \rangle & \mapsto_E s \mid \eta \triangleleft \langle \eta, f.x.e \rangle \end{array}$$

- How does application work?

$$(\text{Apply } \langle \eta', f.x.e \rangle \square) \triangleright s \mid \eta \triangleleft v \mapsto_E ?$$



Environments

- We need to save the old environment somewhere, and restore it when returning from the function call
 - in TinyC, we discarded the local decs used in the premise:

$$\frac{(g.l, ss) \Downarrow (g'.l', rv;)}{(g, \{l\ ss\}) \Downarrow (g', rv;)}$$

- Let's use the stack to store the old environment!



The E-machine

- In the E-machine

- we have frames defined exactly as before
- explicit environments, which are a **ordered** sequence of variable bindings

$$\frac{}{\bullet \text{ env}} \qquad \frac{\eta \text{ env}}{x = v, \eta \text{ env}}$$

- stacks in the E-machine are sequences of environments and frames

$$\frac{}{\circ \text{ stack}} \qquad \frac{f \text{ frame} \quad s \text{ stack}}{f \triangleright s \text{ stack}} \qquad \frac{\eta \text{ env} \quad s \text{ stack}}{\eta \triangleright s \text{ stack}}$$

- states in the E-machine include an environment

$$s \mid \eta \triangleright e$$

$$s \mid \eta \triangleleft v$$



The E-machine: Transition Rules

- Variables:

$$s \mid \eta \triangleright x \quad \mapsto_E \quad s \mid \eta \triangleleft v \quad , \text{ if } \eta(x) = v$$

- Application:

$$(\text{Apply } \langle \eta', f.x.e \rangle) \square \triangleright s \mid \eta \triangleleft v \quad \mapsto_E \quad \eta \triangleright s \mid (f = \langle \eta', f.x.e \rangle, x = v, \eta') \triangleright e$$

restore environment from closure,
add binding for argument x and
function f

- Returning from a function call:

$$\eta \triangleright s \mid \eta' \triangleleft v \quad \mapsto_E \quad s \mid \eta \triangleleft v$$

